

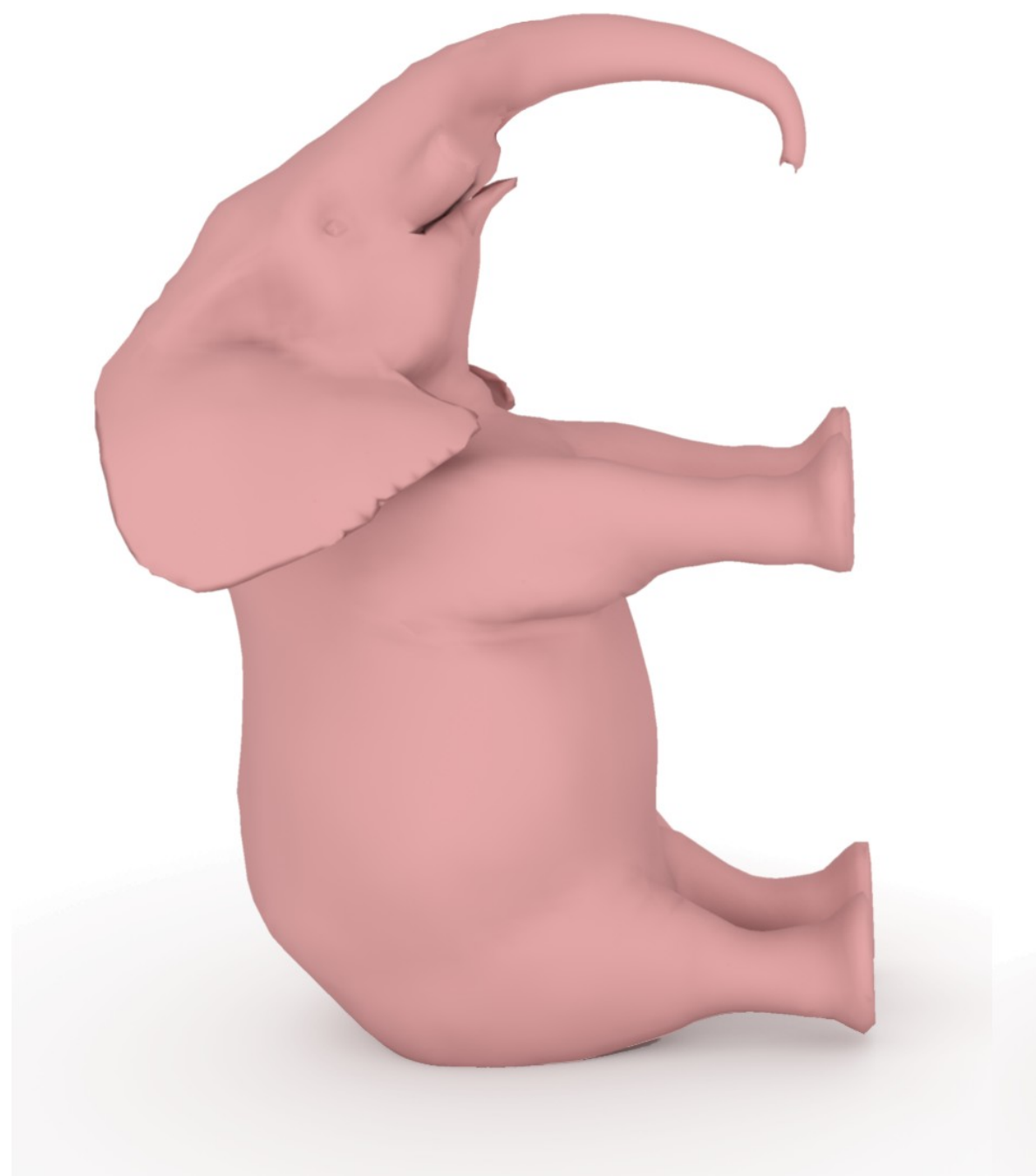
Constant Volume Skinning for Character Animation

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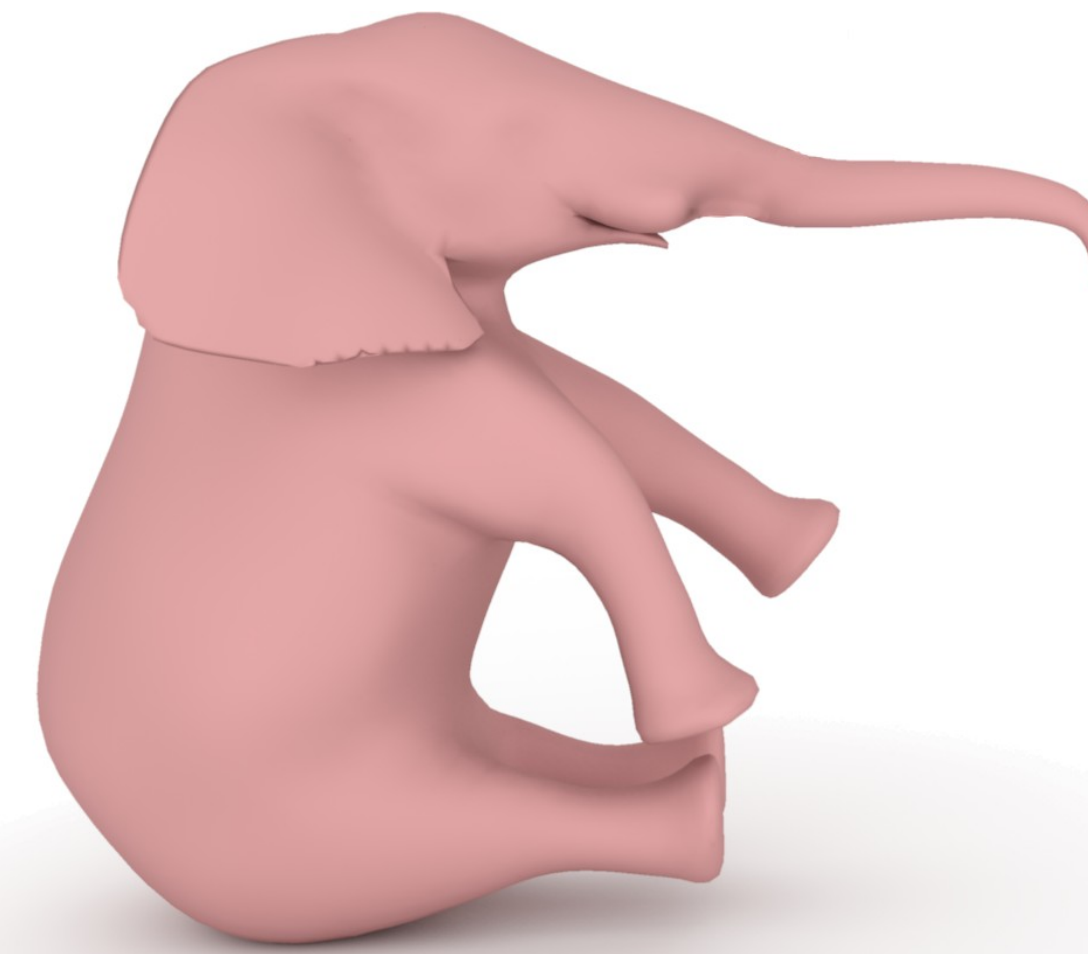
Aim: Quick and intuitive skin deformation for skeleton animation



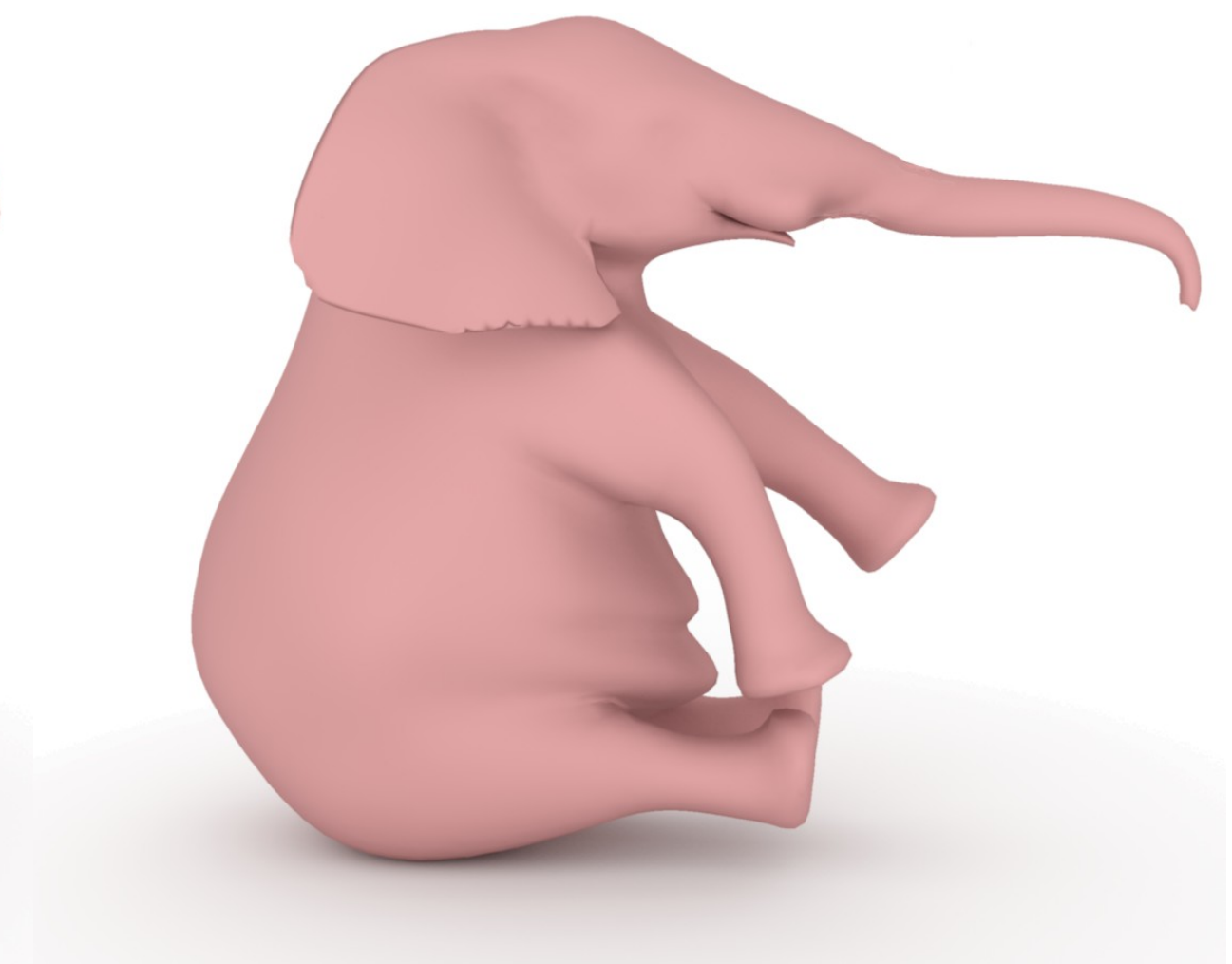
Original shape with skeleton



Original shape



Classical skinning

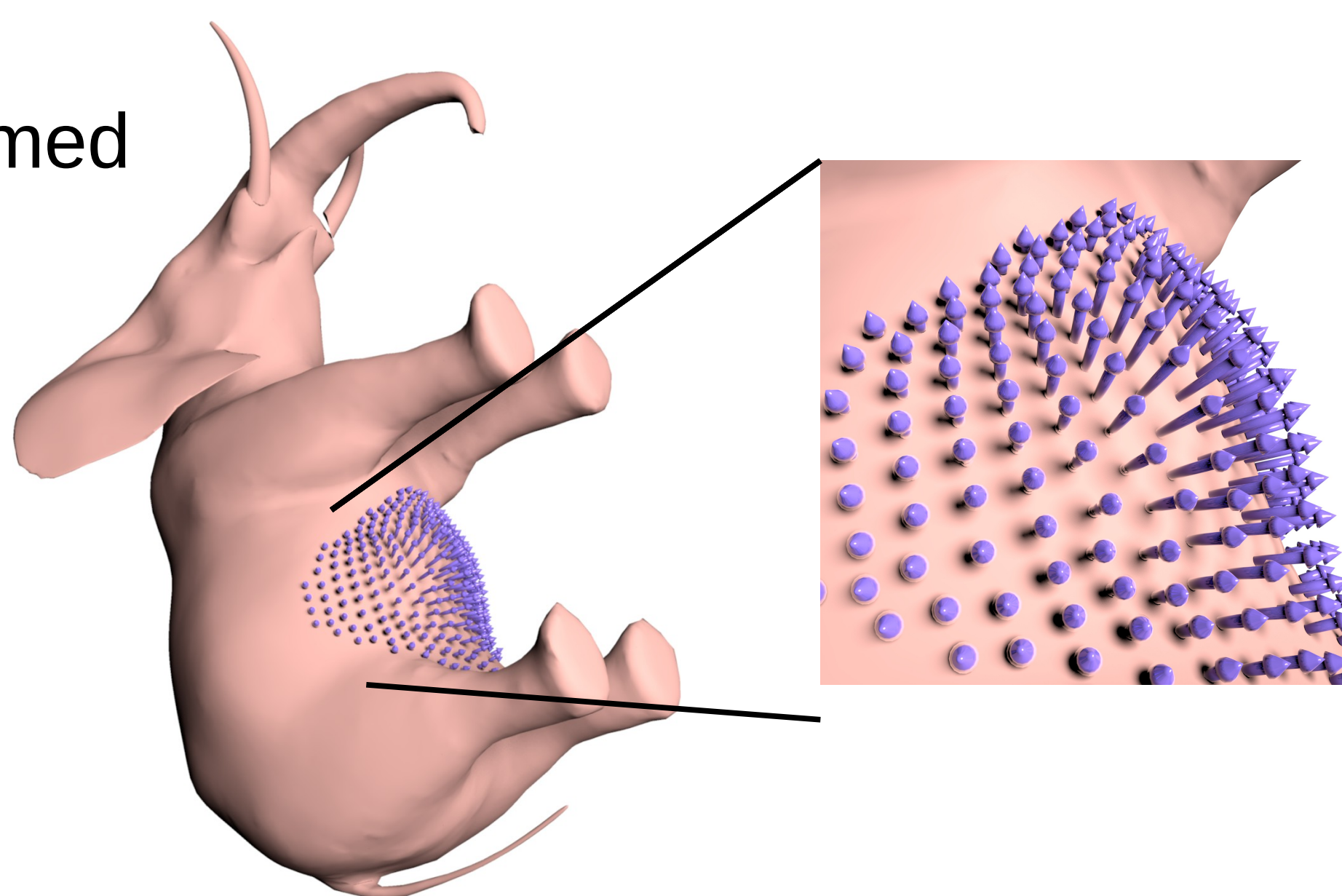


Our method

Two methods to restore the original volume

Normal deformation

Vertices are deformed along the normal direction



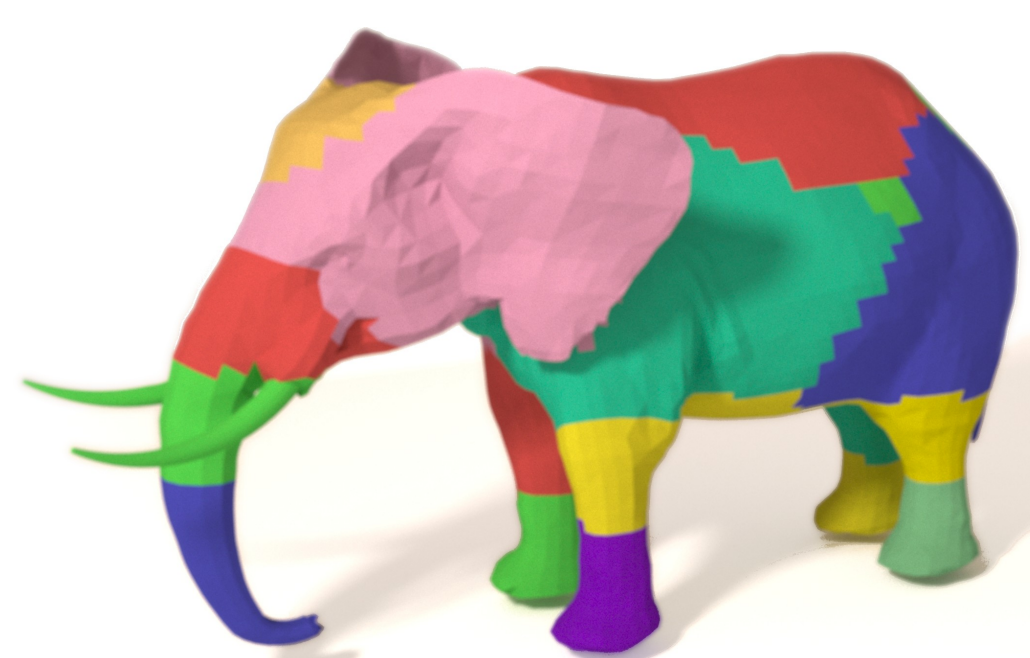
Approximate volume compensation in 1 step

Equation to solve

$$\begin{cases} \min \sum_{k=0}^{N-1} \frac{\rho_k^2}{\gamma_k} & \text{Magnitude of the deformation} \\ & \text{Local weighting} \\ \text{subject to } V(\mathbf{p}_k + \rho_k \mathbf{n}_k) = V(\bar{\mathbf{p}}_k) & \text{Surface normal} \quad \text{Original shape} \end{cases}$$

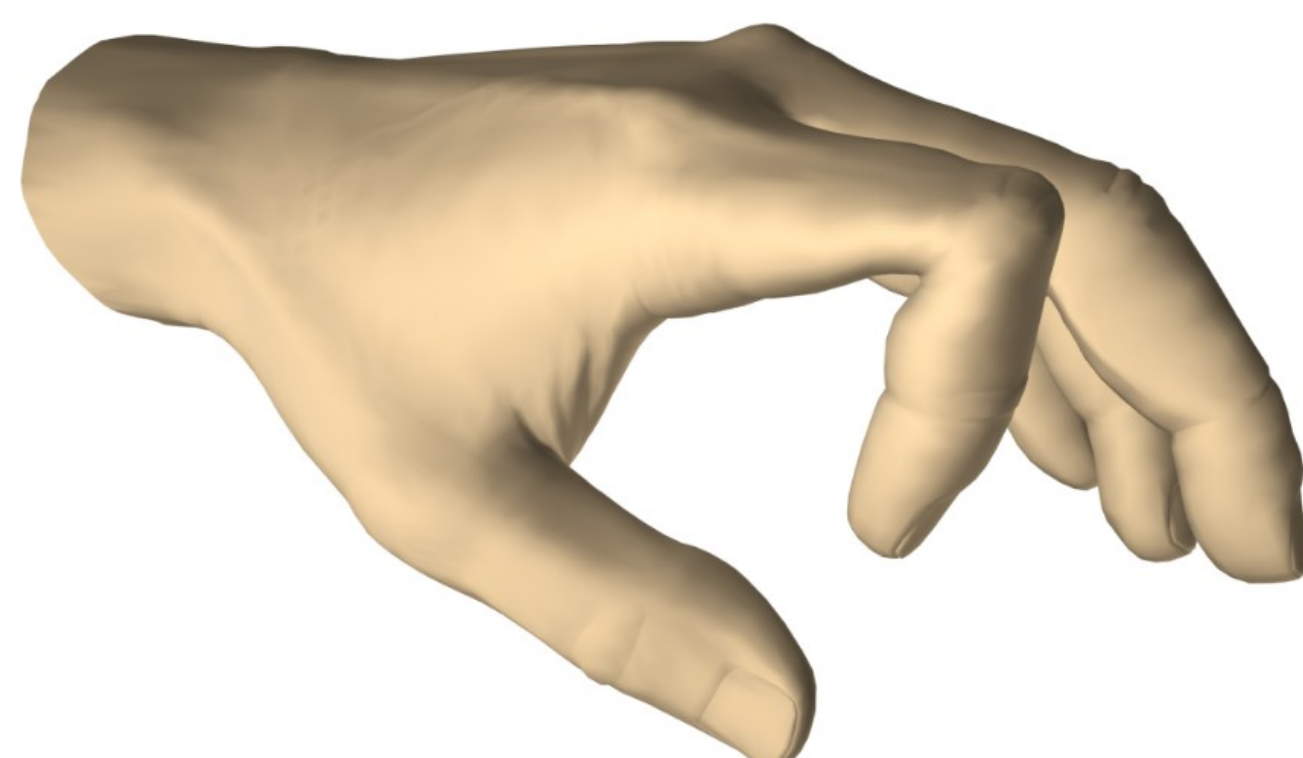
Closed form solution

$$\rho_k = \Delta V \frac{\gamma_k < \mathbf{n}_k, \nabla V(\mathbf{p}_k) >}{\sum_{j=0}^{N-1} \gamma_j < \mathbf{n}_k, \nabla V(\mathbf{p}_k) >^2}$$

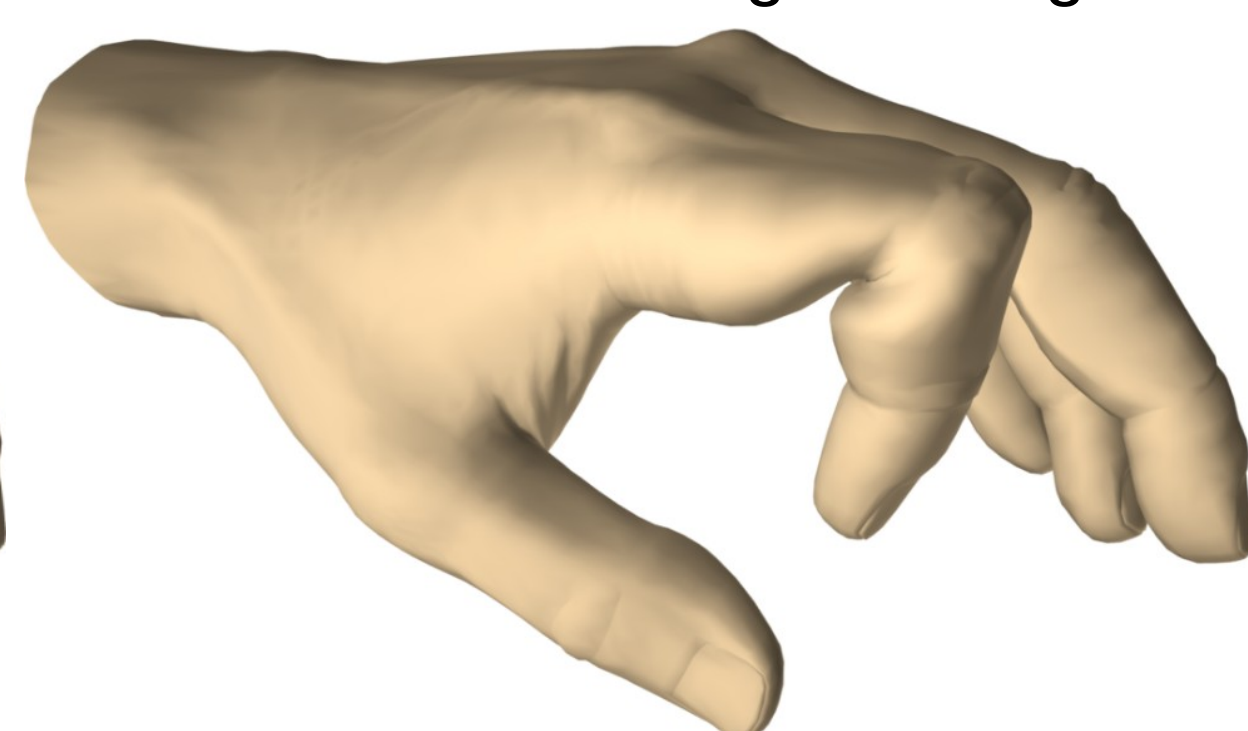


ΔV approximated locally on each segment

Distance (bone, vertex) taken into account to compute local weights. This models the organic bulges effect.



Classical skinning

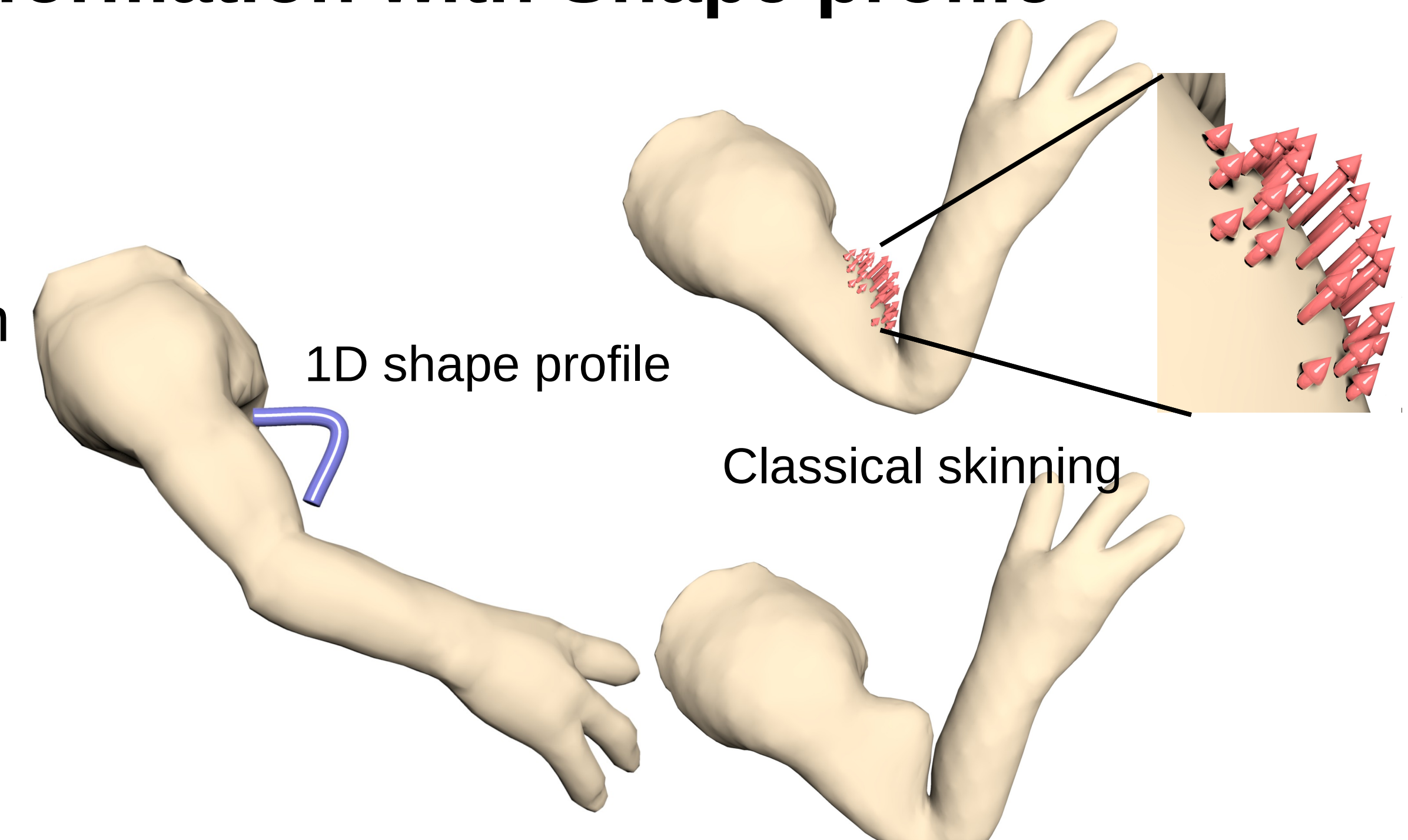


After Volume preservation

- ⊕ Real time
- ⊕ No additional parameter
- ⊖ Approximate volume preservation

Deformation with Shape profile

Vertices are deformed in an arbitrary direction according to a 1D profile



Original shape

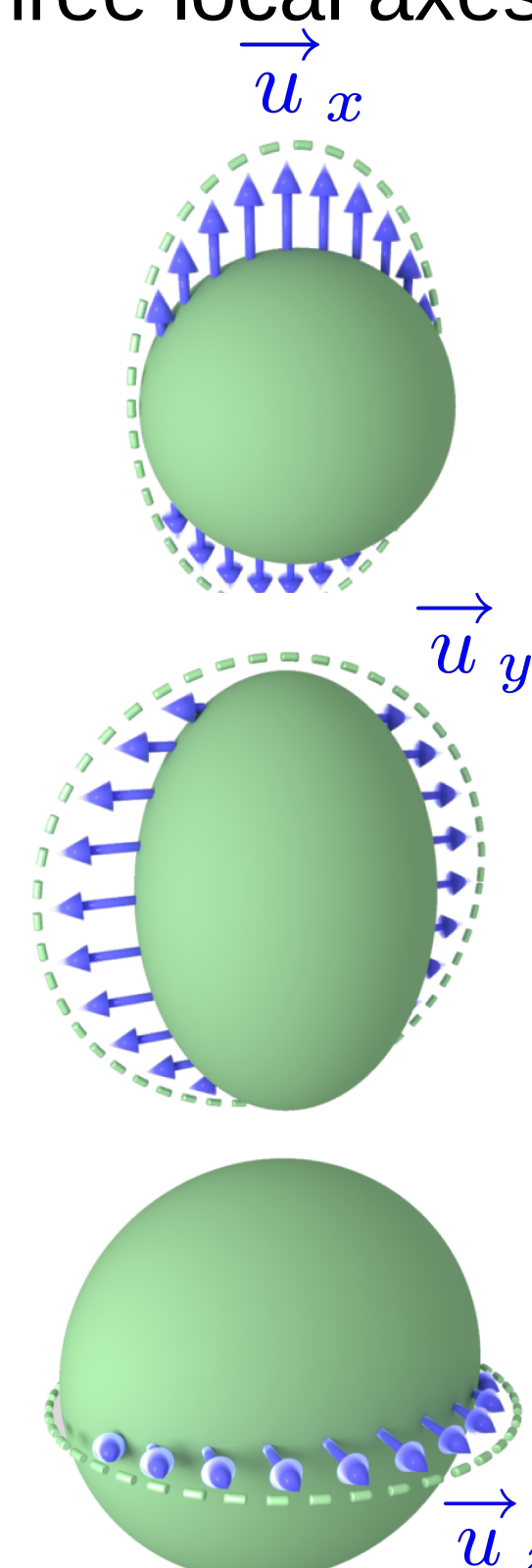
After Volume preservation

Exact volume compensation in 3 steps

$$\begin{cases} \min \sum_{k=0}^{N-1} \frac{\|\mathbf{u}_k\|^2}{\gamma_k} & \text{Vector of deformation} \\ \text{subject to } V(\mathbf{p}_k + \mathbf{u}_k) = V(\bar{\mathbf{p}}_k) \end{cases}$$

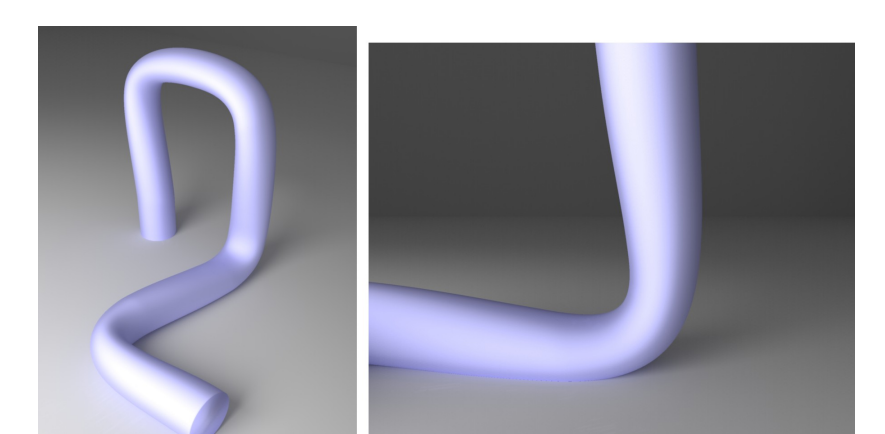
$$\mathbf{u}_k = \gamma_k \Delta V \left(\mu_0 \frac{\frac{\partial V}{\partial x}}{\sum_{j=0}^{N-1} \gamma_j \left(\frac{\partial V}{\partial x} \right)^2}, \mu_1 \frac{\frac{\partial V^*}{\partial y}}{\sum_{j=0}^{N-1} \gamma_j \left(\frac{\partial V^*}{\partial y} \right)^2}, \mu_2 \frac{\frac{\partial V^{**}}{\partial z}}{\sum_{j=0}^{N-1} \gamma_j \left(\frac{\partial V^{**}}{\partial z} \right)^2} \right)$$

Deformation along the three local axes

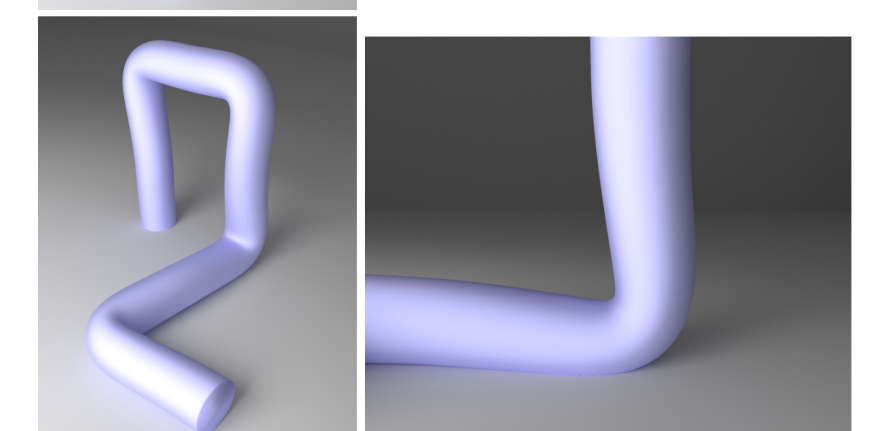


Various correction effects can be parameterized

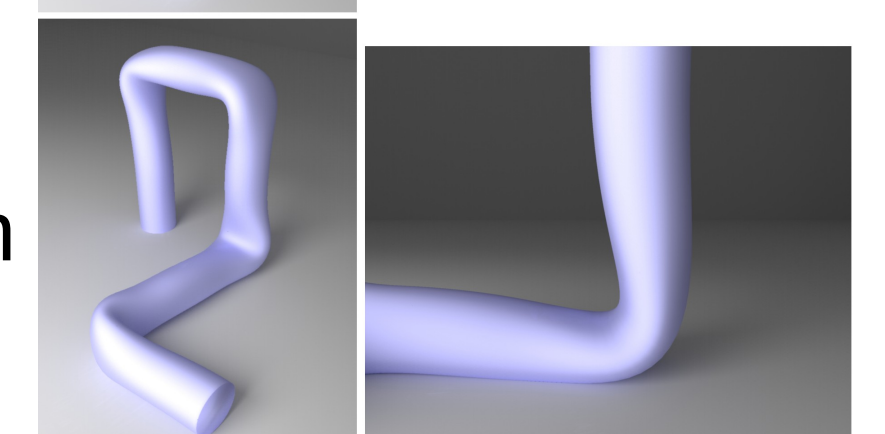
Classical skinning



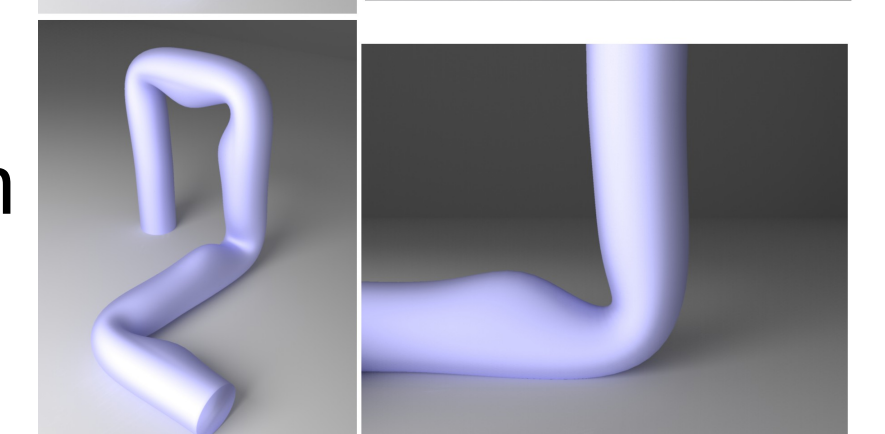
Isotropic correction



Anisotropic correction (rubber effect)



Anisotropic correction (muscular effect)



- ⊕ Exact volume preservation
- ⊕ Control using 1D profile curves
- ⊖ Multiple iterations needed